Rational Inattention

February 18, 2020

Rational Inattention

A formal framework of endogenous information choice

Agents can choose what to observe, i.e. choose D and Σ_{νν} in state space system

$$X_t = AX_{t-1} + Cu_t$$
$$Z_t = DX_t + v_t$$

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• A and C may in equilibrium depend on D and Σ_{vv}

For this to be an interesting question, there has to be costs/constraints associated with acquiring more precise information (otherwise D = I and Σ_{vv} = 0)

Rational Inattention

What is it?

- All information is in principle available, but an agent cannot pay attention to all available information
- Agents have information processing constraints and therefore chooses to observe the most important information

Some history of thought:

- Tools borrowed from information theory
- Sims (Carnegie-Rochester 1998) introduced it to economists
- Price setting model of Mackowiak and Wiederholt (AER 2009) probably the highest impact paper using the method

Information Theory Recap

Entropy

The entropy H(x) of a random variable x with probability mass function p(x) is given by

$$H(x) = -\sum_{x \in \mathcal{X}} p(x) \log_2 p(x)$$

The conditional entropy $H(x \mid y)$

$$H(x \mid y) = -\sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} p(x, y) \log_2 p(x \mid y)$$

quantifies how much uncertainty about variable x remains after observing y.

If x and y are independent

$$H(x \mid y) = H(x)$$

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Mutual Information

The mutual information I(x; y) of x and y is a measure of how much we learn about x given y, and since mutual information is symmetric, i.e. since

$$I(x;y) = I(y;x)$$

it is also how much we learn about y from observing x. Formally, the mutual information of x and y are

$$I(x; y) = H(x) - H(x | y) = H(y) - H(y | x) = I(y; x)$$

Mutual information is independent of scale, i.e. is unaffected by units of measurement.

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Differential Entropy

Differential entropy h(x) is the generalization of entropy to continuous random variables.

Differential entropy of the random variable x with density function p(x) is given by

$$h(x) = -\int p(x) \log_2 p(x) \, dx$$

The conditional entropy $h(x \mid y)$

$$h(x \mid y) = -\int p(x, y) \log_2 p(x \mid y) dxdy$$

quantifies how much uncertainty about variable x remains after observing y.

If x and y are independent

$$h(x \mid y) = h(x)$$

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Coin flip

Coin flip (equal probability binomial)

$$H(x) = -\frac{1}{2}\ln\left(\frac{1}{2}\right) - \frac{1}{2}\ln\left(\frac{1}{2}\right)$$
$$= \ln(2)$$

where ln(2)=1 if the logarithm is taken w.r.t. base 2.

Uniform

Entropy of uniform $x \sim U(0, a)$ is given by

$$h(x) = -\int_0^a \frac{1}{a} \ln\left(\frac{1}{a}\right) dx$$
$$= -\ln\left(\frac{1}{a}\right) = \ln a$$

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The larger the support, the larger the entropy.

Gaussian entropy

The (log) entropy of a Gaussian random vector $x \sim N(0, \Sigma)$ is given by

$$\ln h(x) = \frac{n}{2} \left[\ln 2\pi + 1 \right] + \frac{1}{2} \ln |\Sigma|$$

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where *n* is the dimension of *x* so the interesting part is the determinant of the covariance matrix Σ

Gaussian entropy

For given variances entropy is maximized if x is a vector of uncorrelated variables:

$$\begin{aligned} |\Sigma| &= \left| \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right| = 1 - 0^2 \\ |\Sigma| &= \left| \begin{bmatrix} 1 & a \\ a & 1 \end{bmatrix} \right| = 1 - a^2 \\ -1 &< a < 1 \implies 1 - a^2 < 1 \end{aligned}$$

Intuition: If a = -1 or a = 1 we can perfectly transmit a two dimensional vector using a one dimensional signal

Rational Inattention in a Simple Decision Problem

Gaussian signals and states

In economic (Gaussian) applications the constraint often takes the form

$$\begin{split} h(x) - h(x \mid z) &\leq e^{\frac{1}{2}\kappa} \\ \left(\frac{n}{2}\left[\ln 2\pi + 1\right] + \frac{1}{2}\ln|\Sigma_{prior}|\right) - \left(\frac{n}{2}\left[\ln 2\pi + 1\right] + \frac{1}{2}\ln|\Sigma_{post}|\right) &\leq \frac{1}{2}\kappa \\ &\ln|\Sigma_{prior}| - \ln|\Sigma_{post}| &\leq \kappa \end{split}$$

That is, the decrease in uncertainty from prior to posterior beliefs cannot be too large.

In a Kalman filter setting, the above constraint would be

$$\ln \left| P_{t|t-1} \right| - \ln \left| P_{t|t} \right| \le \kappa$$

The "No forgetting" constraint

Posterior uncertainty cannot be larger than prior uncertainty

$$diag(\Sigma_{prior}) > diag(\Sigma_{post})$$

That is, an agent cannot intentionally increase the variance of the estimation error of one variable in order to get a more precise estimate of another variable.

Rational inattention and entropy in economics

Some nice properties:

- 1. When information processing capacity is large, behavior is close to full information
- 2. When a decision maker allocates a lot of attention to observing one variable, mistakes in responses to that variable becomes small
- 3. A decision maker need to allocate more attention to a variable (with given variance) to achieve a given precision if the variable has low serial correlation

Utility function

$$U = -E\left[(1-\lambda)(a-x_1)^2 + \lambda(a-x_2)^2\right] : 0 < \lambda < 1$$

FOC:

$$2(1-\lambda)(a-E[x_1])+2\lambda(a-E[x_2])=0$$

so that

$$a = (1 - \lambda) E[x_1] + \lambda E[x_2]$$

Plugging in a into U gives the expected loss

$$EU = (1 - \lambda)^2 \sigma_1^2 + \lambda^2 \sigma_2^2$$

where σ_1^2 and σ_2^2 are the posterior error variances of the estimates of x_1 and x_2 .

Choose noise in signal Z to maximize expected utility (i.e. minimize expected loss)

$$Z = \left[\begin{array}{c} x_1 \\ x_2 \end{array}\right] + v$$

subject to

$$\ln |\boldsymbol{\Sigma}_{\textit{prior}}| - \ln |\boldsymbol{\Sigma}_{\textit{post}}| \leq \kappa$$

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For simplicity, we can restrict ourselves to diagonal covariance matrices

The capacity constraint

$$\begin{aligned} \ln |\Sigma_{prior}| - \ln |\Sigma_{post}| &\leq \kappa \\ \frac{|\Sigma_{prior}|}{|\Sigma_{post}|} &\leq e^{\kappa} \\ \frac{|\Sigma_{prior}|}{e^{\kappa}} &\leq |\Sigma_{post}| = \sigma_1^2 \sigma_2^2 \\ \frac{|\Sigma_{prior}|}{e^{\kappa}} (\sigma_1^2)^{-1} &\leq \sigma_2^2 \end{aligned}$$

If Σ_{prior} is diagonal, the optimal Σ_{post} is also diagonal.

Use that inequality will always be binding in an interior solution and plug into expected loss

$$(1-\lambda)^2 \sigma_1^2 + \lambda^2 \frac{|\Sigma_{prior}|}{e^{\kappa}} (\sigma_1^2)^{-1}$$

F.o.c.

$$(1 - \lambda)^{2} - \lambda^{2} \frac{|\boldsymbol{\Sigma}_{prior}|}{e^{\kappa}} (\sigma_{1}^{2})^{-2} = 0$$
$$\frac{\lambda}{(1 - \lambda)} |\boldsymbol{\Sigma}_{prior}|^{\frac{1}{2}} e^{-\frac{1}{2}\kappa} = \sigma_{1}^{2}$$

What happens when $\lambda \rightarrow 1$? And when $\lambda \rightarrow 0$?

Remember the "No forgetting" constraint!

Make sure that

$$diag(\Sigma_{prior}) > diag(\Sigma_{post})$$

by checking that

$$rac{\lambda}{(1-\lambda)} \left| \Sigma_{prior}
ight|^{rac{1}{2}} e^{-rac{1}{2}\kappa} < \sigma_{1,prior}^2$$

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If inequality is violated at marginal condition, set $\sigma_1^2 = \sigma_{1,prior}^2$.

Application: A macro price setting model Optimal Sticky Prices under Rational Inattention

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Application: A macro price setting model

Optimal Sticky Prices under Rational Inattention by Mackowiak and Wiederholt (AER 2009):

- Sets up a macro price setting model with rational inattention
- Explains large and persistent real effects of shocks to money supply
- Can match micro data on large magnitude of individual price changes, while aggregate price changes are small

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Application: A macro price setting model

The optimal price of a good produced by firm i is given by

$$p_{it} = E\left[p_t + ay_t + bz_{it} \mid s_{ti}\right]$$

where p_t is the aggregate price level, y_t are aggregate shocks and z_{it} are firm specific shocks.

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Application: A macro price setting model

The signal vector s_{ti} is chosen to minimize

$$L_{i} = cE\left[\left(X_{t} - X_{t|t}\right)\left(X_{t} - X_{t|t}\right)'\right]c'$$

subject to

$$I(X_t; s_{ti}) \leq K$$

where

$$X_t = \left[\begin{array}{cc} p_t & y_t & z_{it} \end{array} \right]'$$

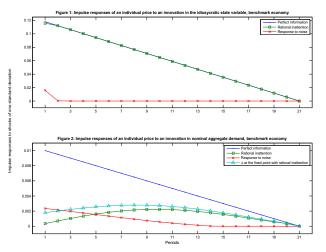
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Some important properties of the model

- Optimal price in increasing in aggregate price level
- Idiosyncratic shocks are large relative to aggregate shocks
- Capacity K is set so that pricing errors are quite small
- Observing endogenous signals (like the price level) also uses up capacity.

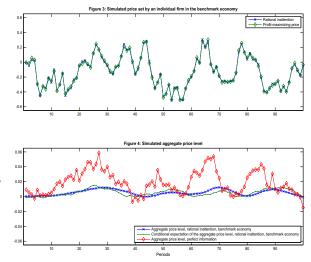
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Price responses to idiosyncratic and aggregate shocks



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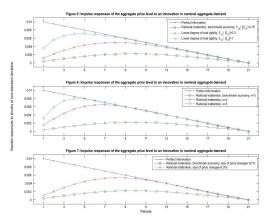
Pricing errors and the importance of feedback



Log-deviations from the non-stochastic soluti

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Changing parameters



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Critique, limitations and further issues

Critique, limitations and further issues

The rational inattention framework yields nice results, and as a theory of information processing it has many appealing features. However, there are also some unresolved issues:

- How can the capacity constraint K be calibrated? In engineering, this is usually a physical constraint. What does it mean for humans? Are we Gaussian channels?
- Can processed information be traded?
- There appears to be markets for information. How do they fit in?
- Is it reasonable to assume that cost of information depends on prior beliefs?

Is it reasonable that entropy alone determines how hard a variable is to form an estimate about?

Other approaches

Rational inattentiveness: Mankiw and Reis (2002), Reis (2006a,2006b)

- Agents update information sets infrequently
- Random (Calvo-type) determination of exactly when updates occur, but frequency can be micro founded with fixed cost of gathering information
- When agents update, they observe state perfectly
 - Results in hierarchical information sets and keeps solution simple

Is it plausible?

- Actions changes even when information is not updated which implies smooth trajectories with intermittent jumps
- Since all agents that update in period t will choose the same action, you will have clustered actions which is not what we see in the data

But then again, maybe it is a tractable short cut that captures aggregate dynamics well